

# MICEDD

## DEEPWATER DEVELOPMENT

28 - 30 March 2023 | Millennium Gloucester Hotel | London, UK

ORGANIZED BY



Quest Offshore

World Oil®



## Uncrewed Surface Vehicles (USV) Network Initiative in support to EOOs



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L. Grare

**MCEDD**  
DEEPWATER DEVELOPMENT  
Managing the Volatile Market Together

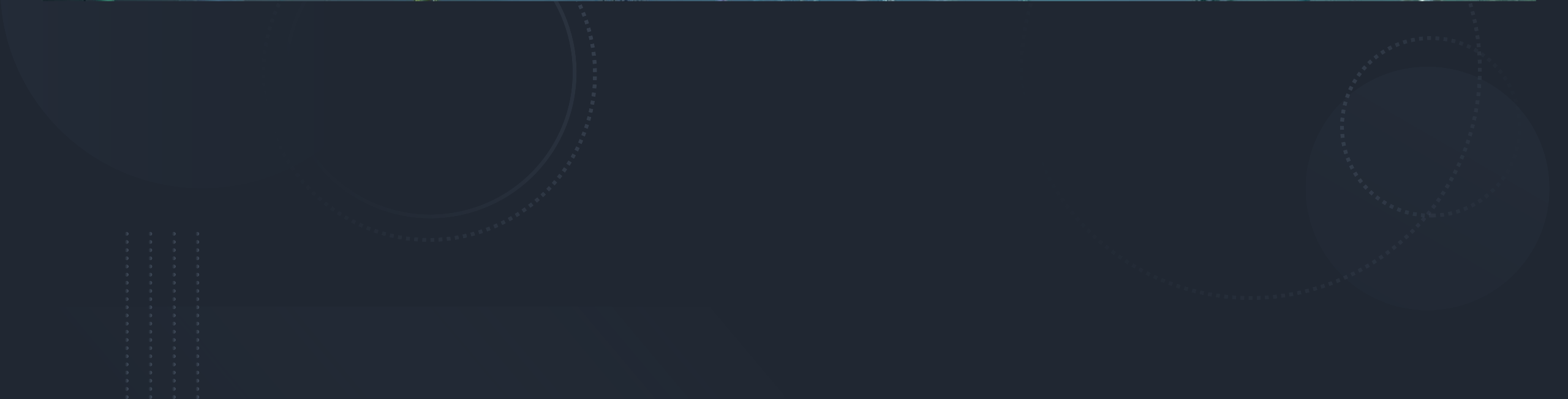
28-30 March, 2023  
Millennium Gloucester Hotel  
London, UK

**EuroSea**



**O**i oceanology  
international®  
**2022** 15-17 MARCH 2022  
LONDON, EXCEL

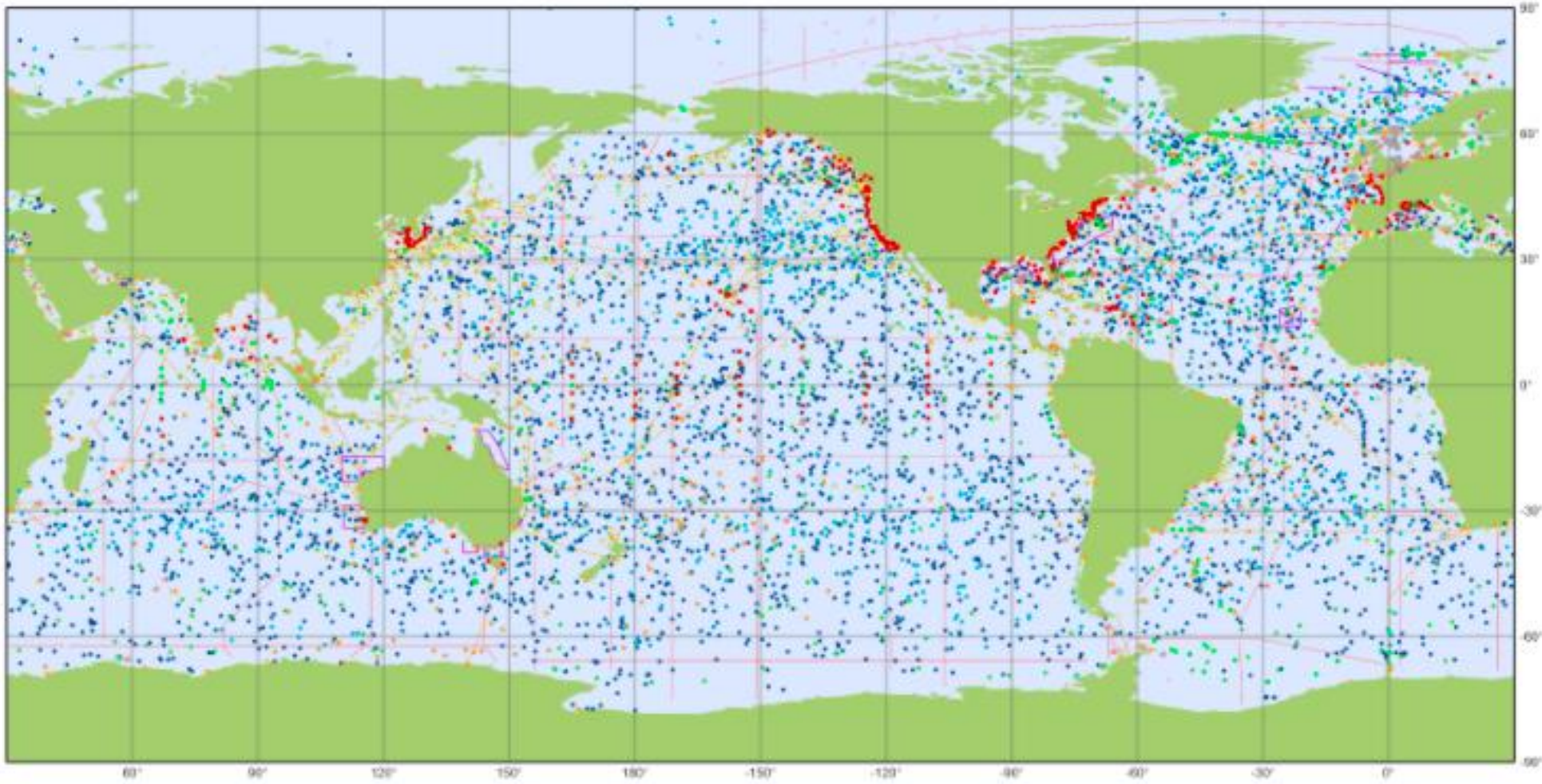
29 companies exhibiting USV tech!!!





- Floats
- Moorings
- UW-gliders
- Research Vessels
- Sea-Level Gauges
- HF Radar
- FerryBox
- Animal-borne Instruments





### Global ocean observing system

January 2022

In situ operational platforms monitored by OceanOPS

#### Mobile systems

- Core floats - Argo
- Deep floats - Argo
- Biogeochemistry floats - Argo
- Underwater gliders - OceanGliders
- Drifting buoys - DBCP

- Polar buoys - DBCP
- Animal borne sensors

#### Fixed systems

- ▲ Tsunameters - DBCP
- Offshore platforms - DBCP
- Moored buoys - DBCP

- Ocean reference stations - OceanSITES

- Sea level gauges - GLOSS

- High Frequency radars

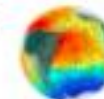
#### Ship based measurements

- Manned weather stations - SOT/VOS
- Automated weather stations - SOT/VOS

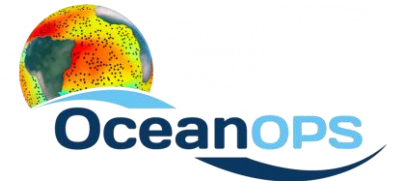
- Radiosondes - SOT/ASAP

#### Reference lines and areas

- Repeat hydrography - GO-SHIP
- eXpendable BathyThermographs - SOT/SOOP
- Sampled sites - OceanGliders



Generated by ocean-ops.org, 2022-02-06





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- Floats
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- Animal-borne Instruments
- **Uncrewed Surface Vehicles -USV**



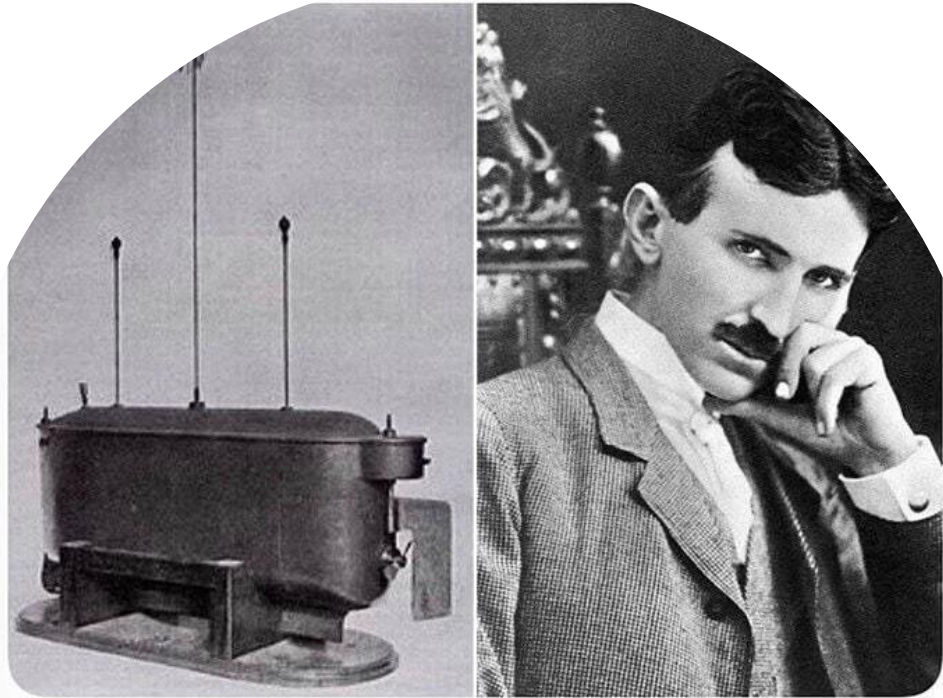




# What exactly is an Uncrewed Surface Vehicle?



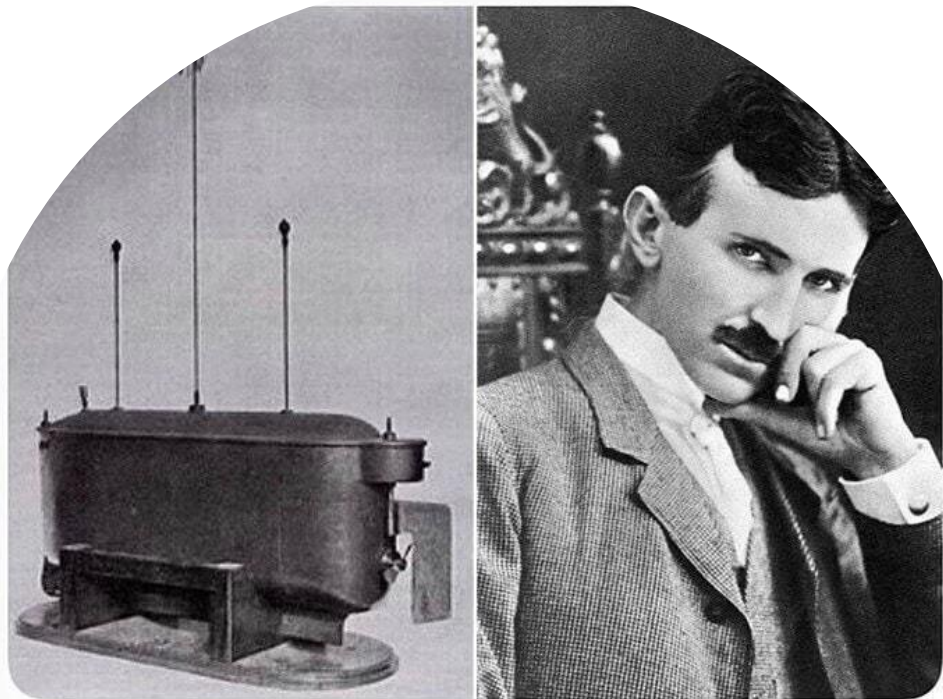
# USV-tech SoA in brief...



In 1898, Nikola Tesla built a remote control boat and displayed it in Madison Square Garden. The crowd thought that he was controlling it with his mind, but a trained monkey was inside. When Tesla noticed the reaction of the crowd, he decided to try something else. He was believing that they could control the boat by shouting commands.

**1898**

# USV-tech SoA in brief...



In 1898, Nikola Tesla built a remote control boat and displayed it in Madison Square Garden. The crowd thought that he was controlling it with his mind because a trained monkey was inside. When Tesla noticed the reaction of the crowd, he decided to try something else. He started shouting commands, believing that they could control the boat.

1898



2021

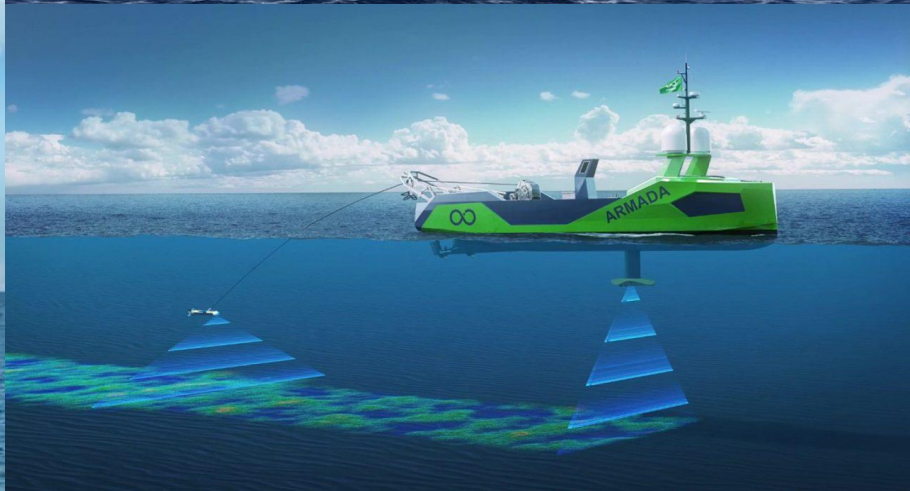


Country	Year	USV Name	Research Purpose & Major Achievements
USA	1993	ARTEMIS (Vaneck et al., 1996)	1) Systems test; 2) Bathymetry sampling
	1996	ACES (Manley, 1997)	1) Oceanographic data collection
	1998	SCOUT (Goudey et al., 1998)	1) Cooperative control; 2) Testbed
	1990s	Roboski (Bremer et al., 2007)	1) Surveillance; 2) Target drones
	1990s	Owls USVs (Motwani, 2012)	1) Harbor and ship security
	2000	AutoCat (Manley et al., 2000)	1) Survey of shipwreck
	2001	Spartan Scout (Motwani, 2012)	1) Port surveillance; 2) Force protection
	2003	USSV-HTF (Motwani, 2012)	1) Towing various sensors and effectors
	2005	WASP (Mahacek, 2005)	1) Stability test; 2) Bathymetric mapping
	2005	Seadoo Challenger 2000 (Ebken et al., 2005)	1) Collision avoidance; 2) Autonomous recovery
	2005	HUSCy (Curcio et al., 2005)	1) Hydrographic survey
	2008	Wave Glider (Bingham et al., 2012)	1) Data collection
	2008	Nereus (Beck et al., 2009)	1) Stability test; 2) Bathymetric mapping
	2009	SeaWASP (Furfaro et al., 2009)	1) Environmental monitoring; 2) Testbed
UK	2010	Piranha (Yang et al., 2011)	1) Reconnaissance
	2011	MUSCL (Bertram, 2008)	1) Surveillance and reconnaissance
	1990s	MIMIR (Roberts & Sutton, 2006)	1) Shallow water search and survey
	2000s	C-series USVs (Anonymous, 2014a)	1) Assets security; 2) Environmental monitoring; 3) Mining
	2000s	FENRIR (Roberts & Sutton, 2006)	1) Relay between UUV and control center
	2000s	Sentry (Murray, 2008)	1) Harbor and shore survey and protection
	2003	SWIMS (Roberts & Sutton, 2006)	1) Mine sweeping
	2003	SeaFox (Yakimenko & Kragelund, 2011)	1) Maritime security operations
	2004	Springer (Naeem et al., 2008b)	1) Environment monitoring; 2) Test platform
	2008	Blackfish (Sonnenburg, 2012)	1) Harbor protection and patrol
Canada	1983	DOLPHIN (Curcio et al., 2005)	1) Bathymetric mapping
	2000s	Barracuda (Bertram, 2008)	1) As sea-surface target system
	2000s	Hammerhead (Bertram, 2008)	1) Simulating a multi-vehicle swarm threat
Italy	2004	SESAMO (Caccia et al., 2005)	1) Environmental sampling
	2005	Charlie (Caccia et al., 2007)	1) Environmental sampling and survey
	2007	ALANIS (Bibuli et al., 2012)	1) Environmental sampling and survey
	2008	U-Ranger (Motwani, 2012)	1) Mine sweeping; 2) Harbor protection
Portugal	2000	CARAVELA (Pascoal et al., 2006)	1) Oceanographic sampling; 2) Testbed
	2004	DELFIN (Alves et al., 2006) and DELFIMX (Gomes et al., 2006)	1) Oceanographic sampling; 2) Communication with UUVs
	2006	ROAZ I & II (Martins et al., 2007a)	1) Search and rescue
Norway	2006	Swordfish (Ferreira et al., 2007)	1) Environmental survey
	2008	Kaasbøll (Breivik et al., 2008)	1) Navigation and control systems test
	2008	Viknes (Breivik, 2010)	1) Multi-purpose system tests
	2000s	Mariner (Breivik, 2010)	1) Environmental surveillance and sampling
Israel	2003	Protector (Breivik et al., 2008)	1) Reconnaissance; 2) Counter-mine
	2005	Seastar (Yang et al., 2011)	1) Port, coastal survey; 2) Reconnaissance
	2005	Stingray (Bertram, 2008)	1) Homeland security and coastguard
Germany	2007	Silver Marlin (Bertram, 2008)	1) Surveillance and reconnaissance
	1998	MESSIN (Majohr & Buch, 2006)	1) Water ecological study
France	2005	Basil (Bertram, 2008)	1) Offshore pipelines survey
	2005	MiniVAMP (Bertram, 2008)	1) Remote survey of offshore pipelines
	2007	Inspector (Yang et al., 2011)	1) Surveillance and reconnaissance
Sweden	2002	Piraya (Yang et al., 2011)	1) Cooperative control
Singapore	2010	Venus (Bertram, 2008)	1) Multi-tasks test
China	2008	Tianxiang One (Yan et al., 2010)	1) Meteorological survey
	2010	USV-ZhengHe (Yang et al., 2011)	1) Inshore marine data collection
Japan	2000	Kan-Chan (Desa et al., 2007)	1) Study of global warming
	2004	UMV series (Bertram, 2008)	1) Ocean and atmosphere exploration
India	2006	ROSS (Desa et al., 2007)	1) Oceanographic sampling



- Propulsion mainly based on electrical thrusters.
- Short-médium range endurance (hours/days) for missions near shore areas.





... USV development concept quite close to autonomous ships?

- Is USV technology paving the way somehow for Autonomous Maritime Navigation strategy?

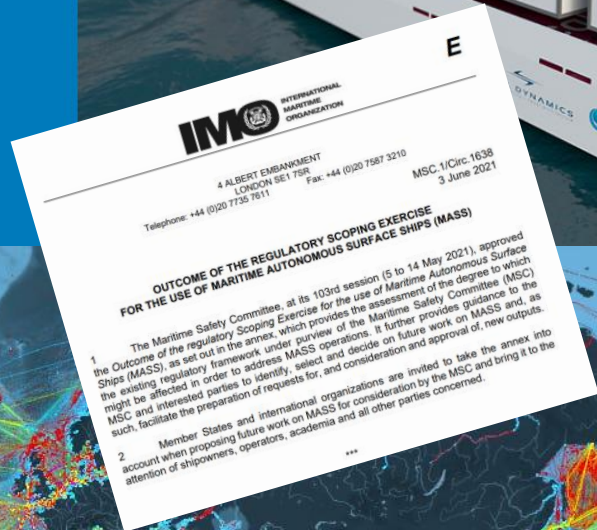
- Should USV and Autonomous Ships development strategies work under a closer and synergetic manner in some fields in order to strength and promote MASS?



INTERNATIONAL  
MARITIME  
ORGANIZATION

25 May 2021

# Autonomous ships: regulatory scoping exercise completed



## Timeline for autonomous ships

2017	2020	2023	2025
Remote monitoring	Fully remote controlled vessel (manned) – unmanned with special approval	Gradual increase of autonomous control	Autonomous ship traffic commercial
Test areas	National pilots	Several pilots globally	Full scale testing / validation
		Domestic authority approval / certificate	Class/IMO reg. in place
International collaboration	Design requirements for autonomous power and propulsion systems Autonomous automobile commercial	Satellite becomes cheaper Mobility as a service "Industry standards in place"	Strongly decreased data communication Infrastructure
Ethical issues			
Development of cyber security			
Projects, IPR, competences, education			
National, IMO and global legislation development			



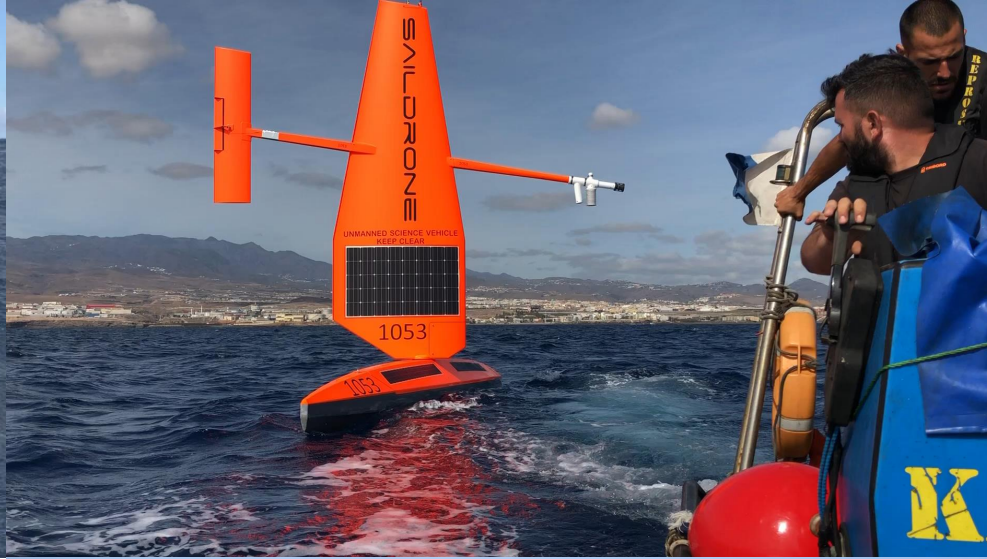
**BEING A RESPONSIBLE INDUSTRY**

Maritime Autonomous Ship Systems (MASS)  
UK Industry Conduct Principles and Code of Practice

A Voluntary Code  
November 2020

COURTESY OF SEA MACHINES ROBOTICS

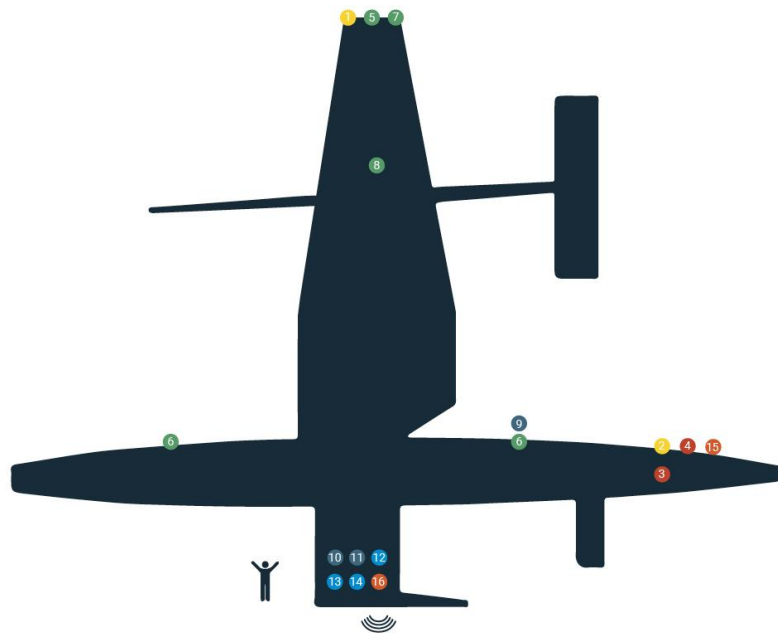




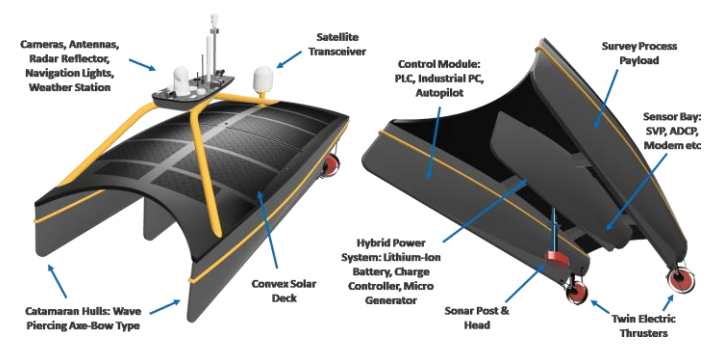
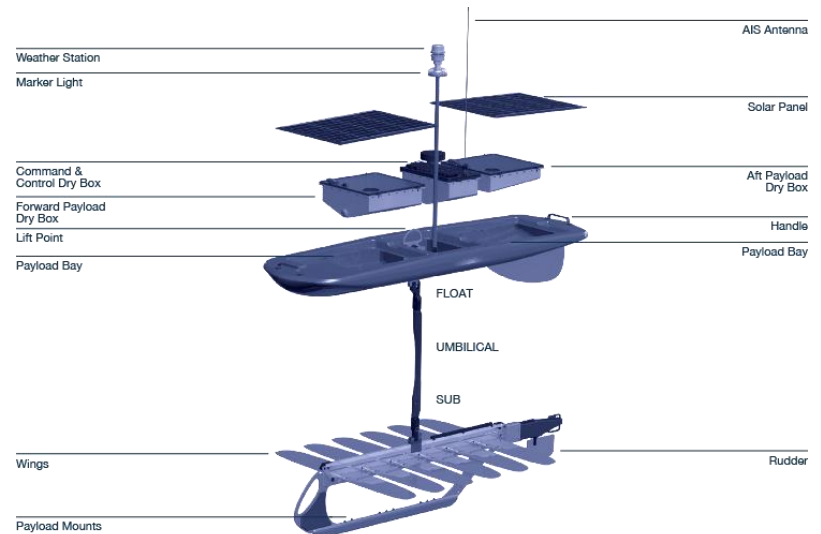
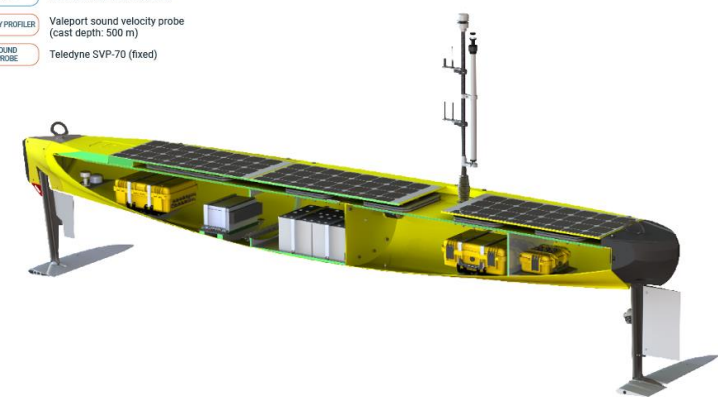
- Propulsion based on **ocean-energy sources** (waves, wind and sunlight). Highly capable to increase **persistent-presence** in the ocean in a more sustainable and efficient **routine-mode operation**.
- Long-range (weeks/months) missions in both coastal and open-ocean areas.

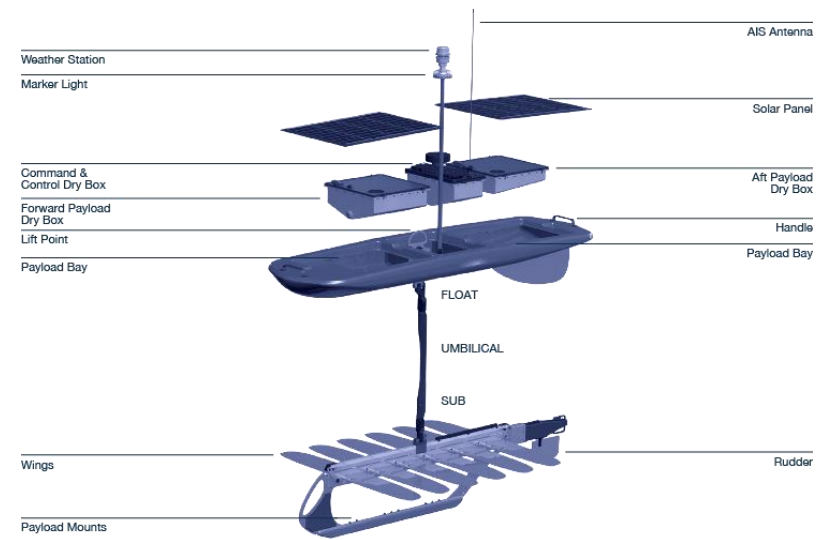


# Why USV are key for Ocean-Observing?

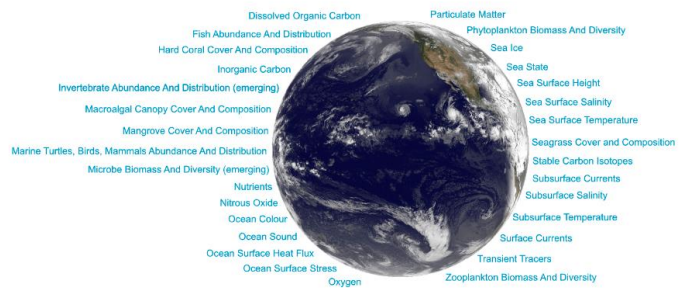


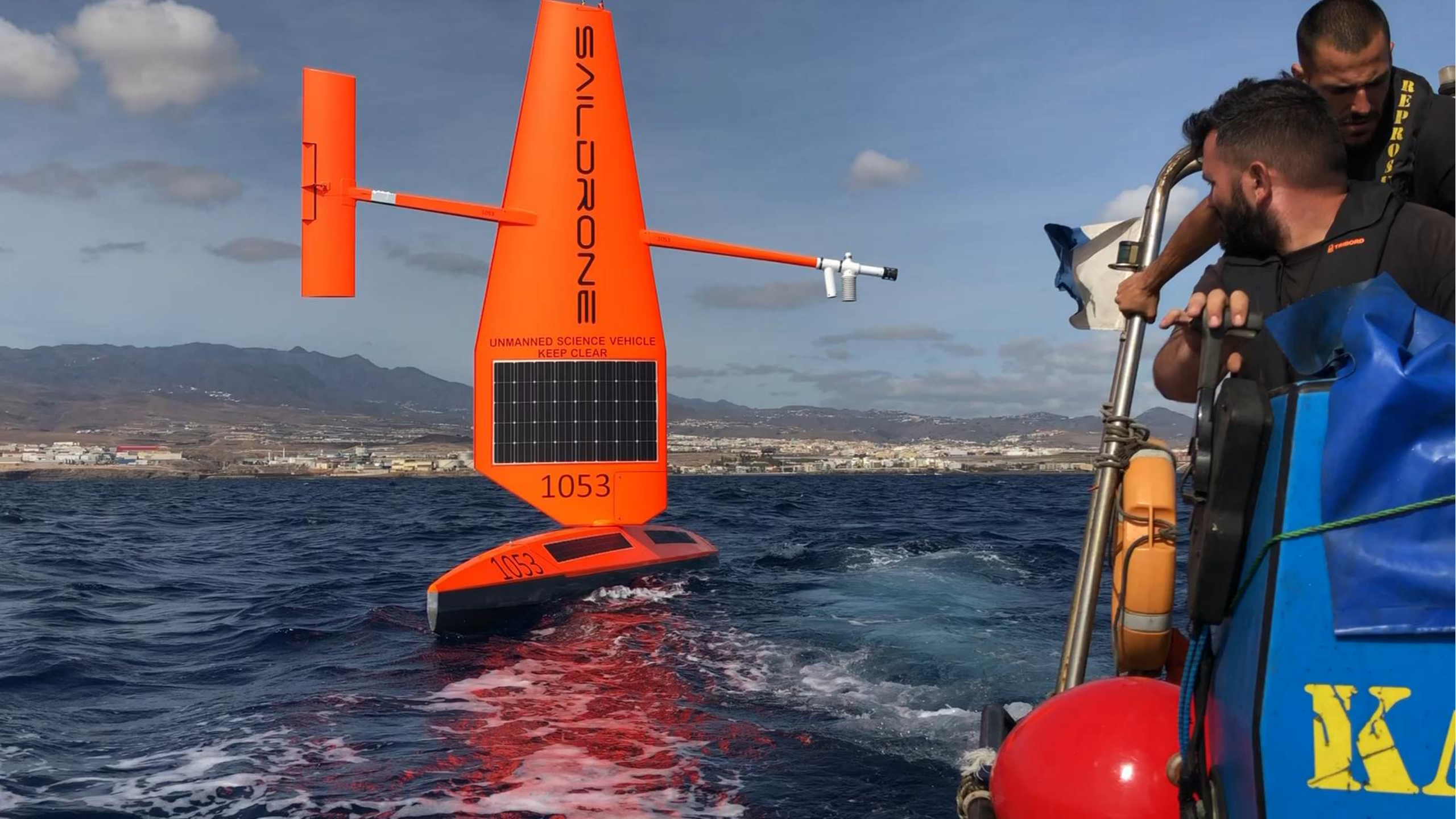
- ATMOSPHERIC MEASUREMENTS
  - 1 WIND SPEED & DIRECTION B&G anemometer
  - 2 ATMOSPHERIC PRESSURE Yacht Devices barometer
- OCEAN MEASUREMENTS
  - 3 WAVE HEIGHT & PERIOD VectorNav VN300 Dual GPS aided IMU
  - 4 WATER SAMPLE COLLECTION MBARI eDNA environmental sample processor
- MARITIME DOMAIN AWARENESS
  - 5 RADAR Furuno Radar
  - 6 SMART CAMERA ARRAY 360° High-resolution optical cameras with AI/ML target detection
  - 7 SMART CAMERA ARRAY 2 x 220° High-resolution optical cameras with AI/ML target detection
  - 8 AIS TRANSCIVER Class A AIS transceiver
- ACOUSTIC MEASUREMENTS
  - 9 BATHYMETRY Seapath 380+ GNSS/INS system
  - 10 BATHYMETRY Kongsberg EM304 multibeam sonar
  - 11 BATHYMETRY Kongsberg EM2040 multibeam sonar
  - 12 OCEAN CURRENTS Simrad EC150 ADCP
  - 13 OCEAN CURRENTS Teledyne Pinnacle 45 ADCP
  - 14 FISH BIOMASS Simrad EK80 echo sounder
  - 15 SOUND VELOCITY PROFILER Valeport sound velocity probe (cast depth: 500 m)
  - 16 SURFACE SOUND VELOCITY PROBE Teledyne SVP-70 (fixed)





**GCOS Essential Climate Variables**





SAILDRONE

UNMANNED SCIENCE VEHICLE  
KEEP CLEAR

1053

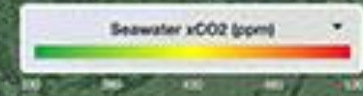
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REPRO

KA

# 2019-2020 Atlantic to Mediterranean (ATL2MED)

A public-private partnership that aims to contribute to a greater understanding of the impacts on the ocean ecosystem and develop a better understanding of the socio-economic impacts of acidification, deoxygenation, ocean processes, and climate change on the communities reliant on the Atlantic and Mediterranean.

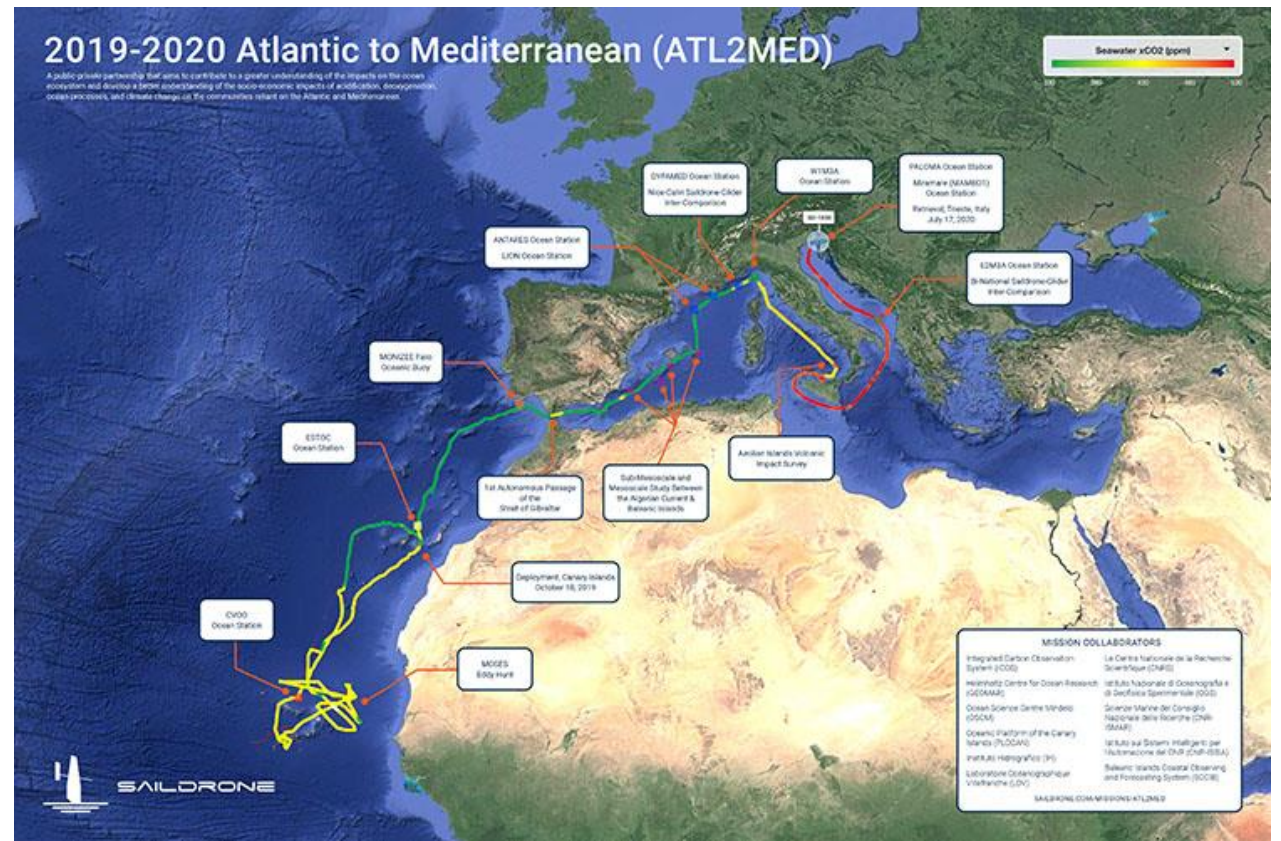
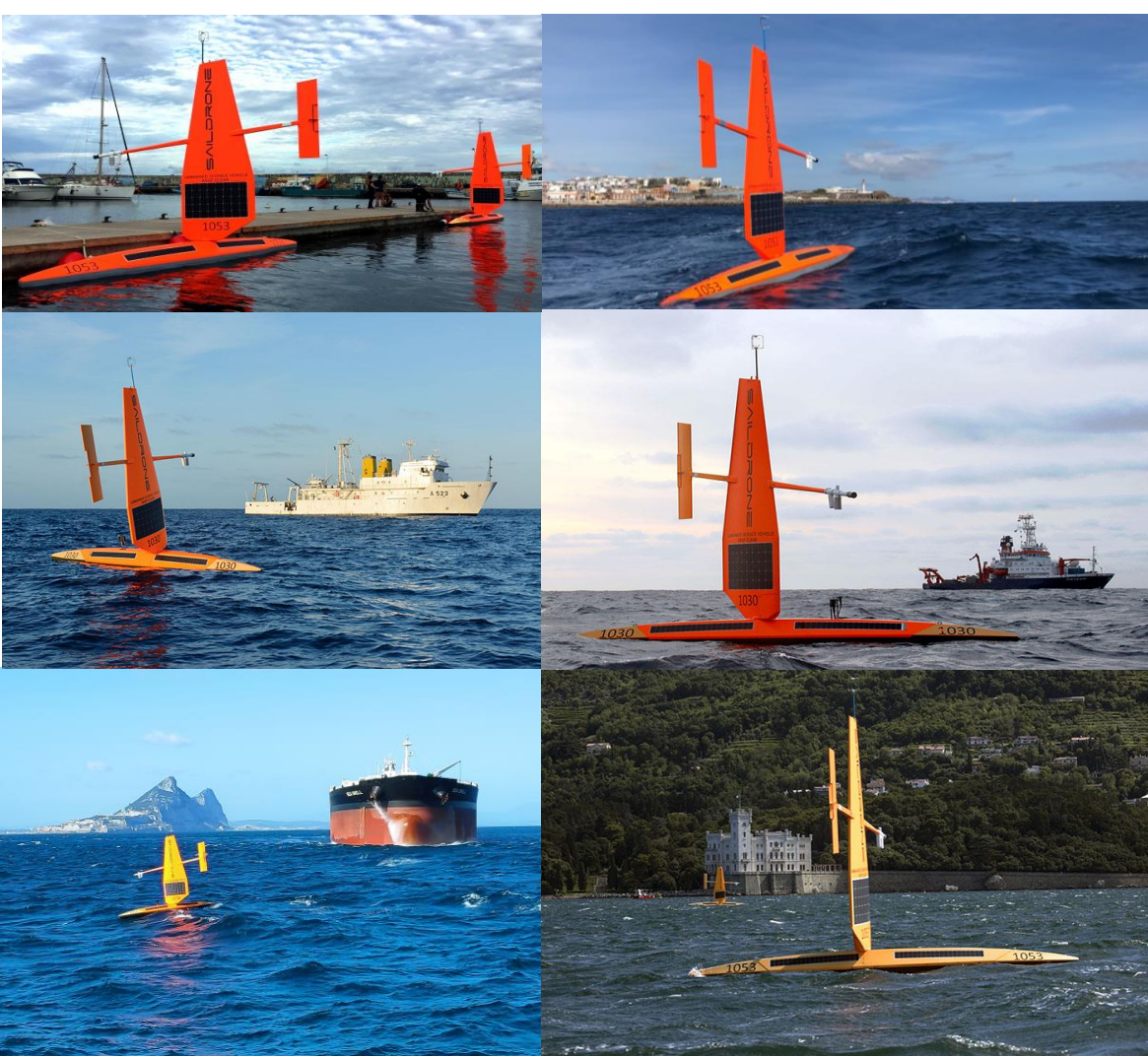


**MISSION COLLABORATORS**

Integrated Carbon Observation System (ICOS)	La Centrale Nationale de la Recherche Scientifique (CNRS)
Woods Hole Oceanographic Institution (WHOI)	Istituto Nazionale di Geografia e di Geofisica Sperimentale (IGGG)
Ocean Science Centre, Ireland (OSCI)	Scienze Marine del Consiglio Nazionale delle Ricerche (CNR-ISMAR)
Oceanic Platform of the Canary Islands (OPCAN)	Istituto per Sistemi Integrati per l'Automazione del CNR (ISIA-ISA)
INMARES Hidrografía (IH)	Balearic Islands Coastal Observing and Forecasting System (BOCOS)
Laboratoire Océanographique de Villefranche (LOV)	

SAILDRONE.COM/MISSION/ATL2MED





EuroSea



EuroGOOS  
European Global Ocean  
Observing System

ICOS  
INTEGRATED  
CARBON  
OBSERVATION  
SYSTEM

emso  
ERIC  
EUROPEAN INTEGRATED  
CARBON OBSERVATION  
SYSTEM

### 2019-2020 ATL2MED Mission Stats

Mission duration	274 days (October 18, 2019 to July 17, 2020)
Distance sailed	15,015 nautical miles (27,810 kilometers or 17,280 miles) – both vehicles combined
Average vehicle speed	2–3 knots (average human walking pace)
Ocean stations visited	9
Data collected	Carbon, (pCO <sub>2</sub> ), acidity, current velocity & direction, wind speed & direction, relative humidity, barometric pressure, air & sea temperature, salinity, dissolved oxygen, chlorophyll, wave height & period, acoustic backscatter





- Technology level (TRL) already well developed and mature.
- Huge Tech&Operational capabilities /uses.
- Wide range of applications/services for key marine and maritime sectors on ocean observing, survey, intervention, etc. already underway.
- **Clear lack at NETWORK level**
  - # Technical
  - # Operations / Missions
  - # Data/Metadata
  - # Legal framework
  - # Best Practices / Standards
  - # ...





**EuroGOOS**  
European Global Ocean  
Observing System

**EuroGOOS**  
**Strategy 2030**

**EOOS** | European Ocean Observing System

**Towards an end-to-end, integrated and sustained ocean observing system for Europe**

Consultation Document

[www.eoos-ocean.eu](http://www.eoos-ocean.eu)



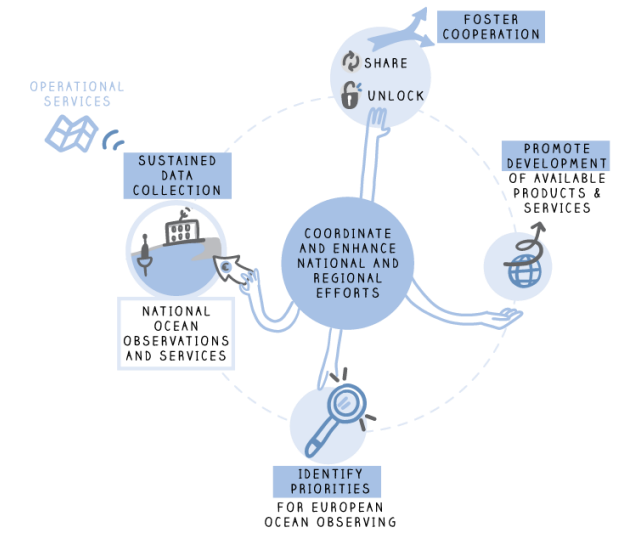
**EOOS** | European Ocean Observing System

**ALIGNING, INTEGRATING AND PROMOTING EUROPE'S OCEAN OBSERVING CAPACITY**

**EOOS** | European Ocean Observing System

**EOOS Strategy 2018-2022**  
OCTOBER 2018

[www.eoos-ocean.eu](http://www.eoos-ocean.eu)



# EuroSea

Improving and integrating the European Ocean Observing and Forecasting System



Project Info Achievements News & Events Ocean Best Practices Contact



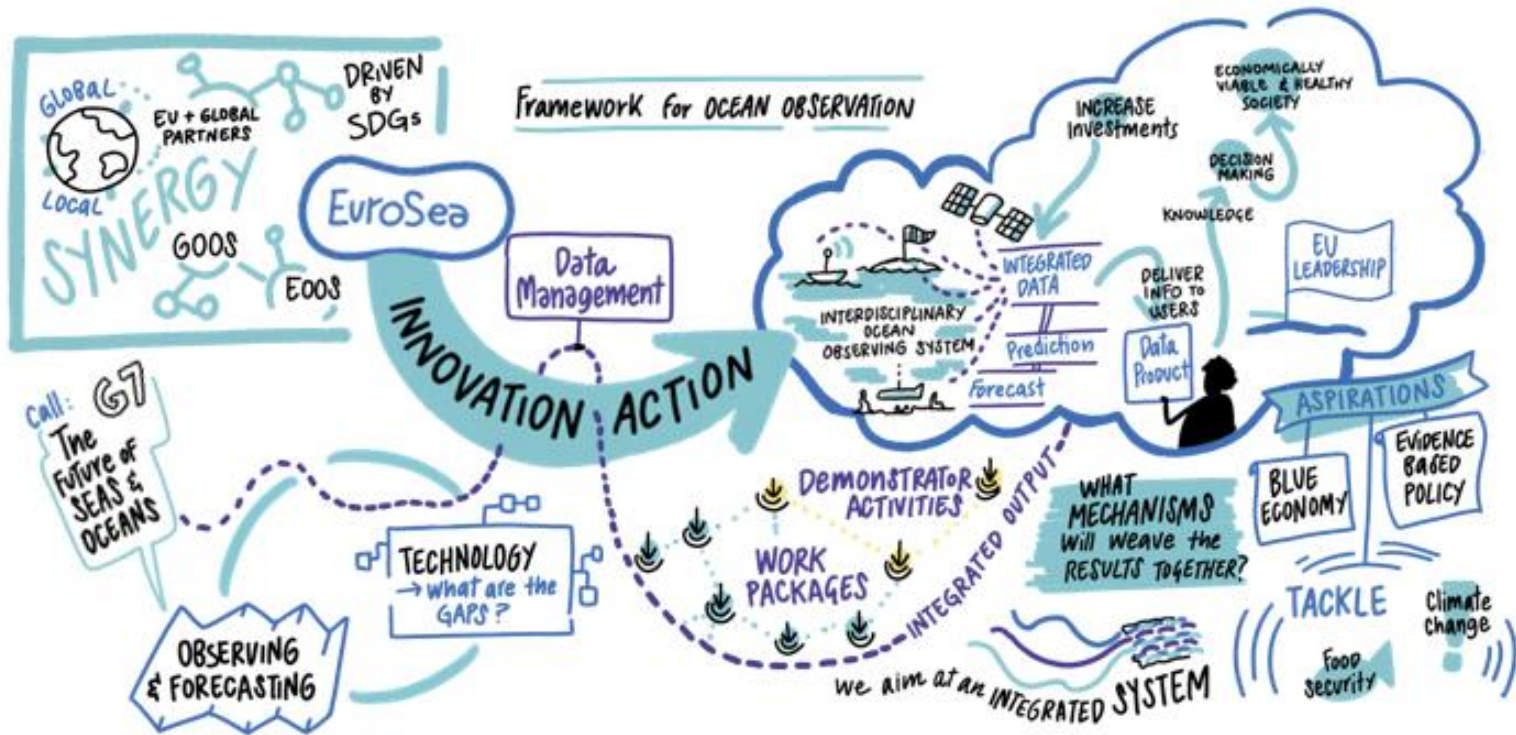
This project has received funding from the European Union's Horizon 2020 research and innovation programme under grant agreement No 862626



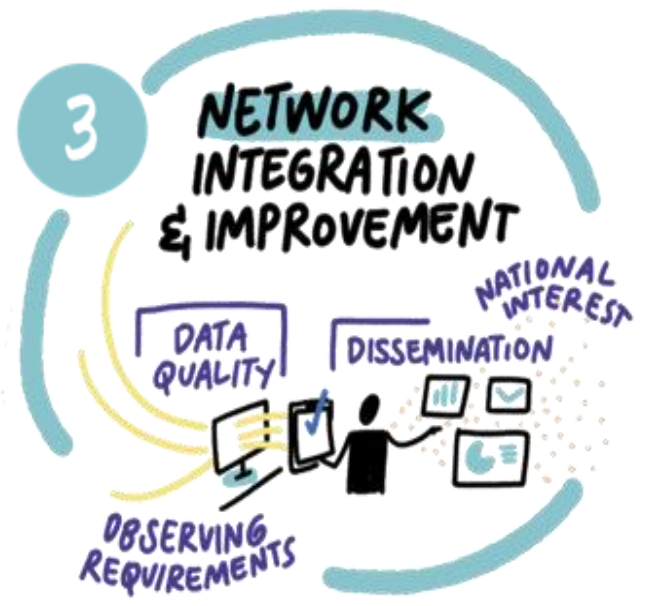
Helmholtz Centre for Ocean Research Kiel

<https://eurosea.eu/>





# EuroSea

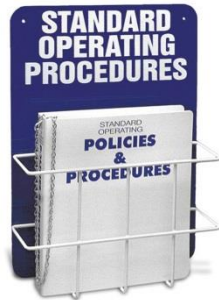


	European networks	Global networks
HF Radar	HF Radar	Global HF Radar
Glider	Glider	Ocean Gliders
Fixed platforms	Fixed Platforms	OceanSITES
Surface vehicle	<i>in progress...</i>	
Profiling floats	EU FP	Argo
Research ships	<i>in progress...</i>	
Commercial ships	FerryBox + ...	

# WP3 – Task 3.7 Autonomous Surface Vehicles Network



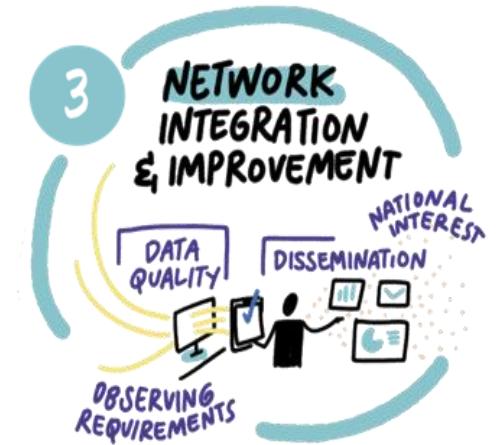
1) ASV-Network definition and roadmap addressed to cover current and future user's needs, including access to infrastructures, community roadmap monitoring, promoting knowledge exchange, enhancement and partnership worldwide with the establishment of an ASV User Group.



2) Improvements on Standard Operating Procedures (SOP) for derived Best Practices (BP) implementation on operational protocols, data management, knowledge transfer, risk assessment, legislation, etc. in order to properly improve the ASV technology, contributing to the E00S implementation plan.



3) Two workshops will be organized aiming at ASV technology - challenges, opportunities and user engagement, and ASV technology - BP implementation.



**PL0CAN**  
Plataforma Oeánica  
de Canarias



**U. PORTO**  
FEUP FACULDADE DE ENGENHARIA  
UNIVERSIDADE DO PORTO

**marum**

**National  
Oceanography Centre**  
NATURAL ENVIRONMENT RESEARCH COUNCIL



Gathering more Knowledge for a Sustainable Use of the Ocean through a Multiplatform-Network approach based on cutting-edge Observing Technologies



## WP3 – Network Integration and Improvement

### Task 3.7

## Autonomous Surface Vehicles (ASV) Network

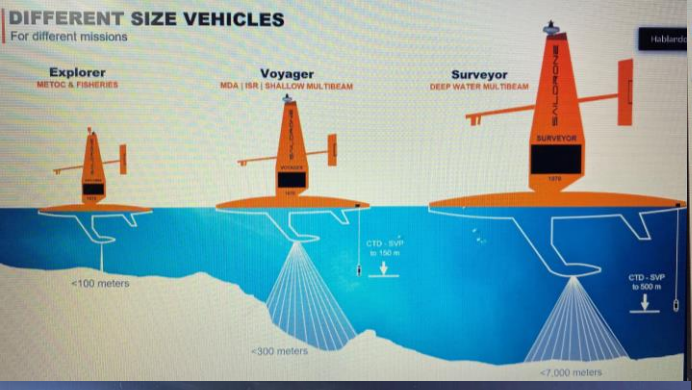
1<sup>st</sup> Workshop (online)  
October 5<sup>th</sup> – 6<sup>th</sup>, 2021











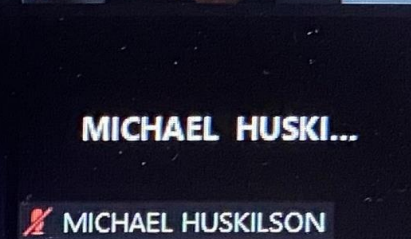
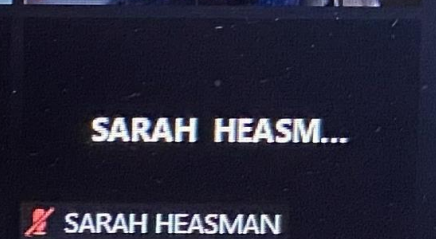
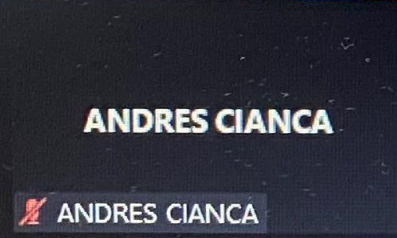



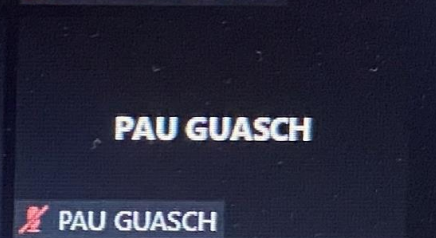
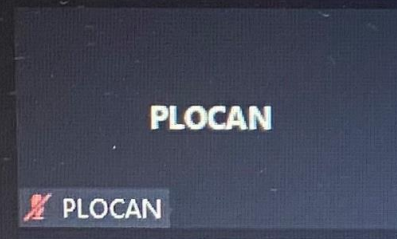



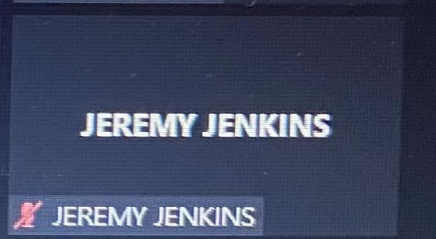

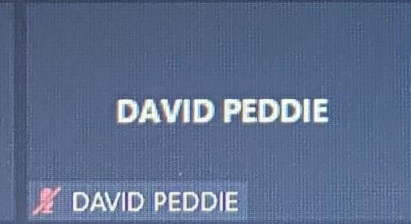
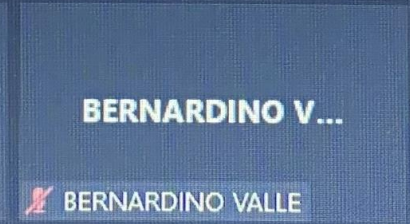
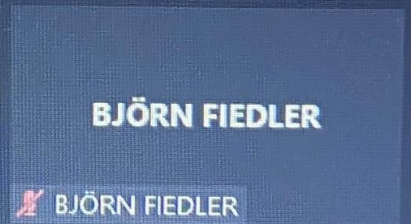
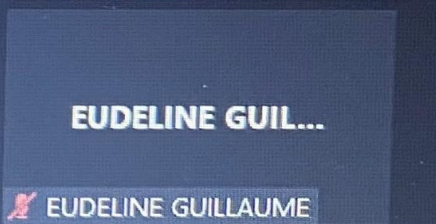
# AGENDA

Oct 5 <sup>th</sup>		Oct 6 <sup>th</sup>	
2:00 PM	Welcome + Workshop goals	2:00 PM	Welcome + Session goals
2:10 PM	EuroSea Project Overview	2:05 PM	EOOS Overview
Session 1 - ASV Technology		Session 3 - ASV Regulatory Framework	
2:20 PM	Offshore Sensing	2:20 PM	National Oceanography Center
2:30 PM	AutoNaut	2:40 PM	DGMM / MITMA
2:40 PM	GPASesbots	3:00 PM	NOAA
2:50 PM	ixblue	3:15 PM	LSTS FEUP
3:00 PM	UTEK	3:30 PM	Panel Discussion
3:10 PM	Seasets	3:40 PM	Panel Discussion
3:20 PM	Saildrone	3:50 PM	Wrap up and closure
3:30 PM	Panel Discussion	4:00 PM	Session 4 - Best Practices and ASV Network Roadmap Definition
Session 2 - ASV Applications / Operations		4:20 PM	EMODNet
4:00 PM	UEA	4:40 PM	ixblue
4:10 PM	GEOMAR	5:00 PM	NOAA
4:20 PM	XOCEAN Ltd.	5:20 PM	MARUM
4:30 PM	Tidewise	5:40 PM	Panel Discussion
4:40 PM	Ocean Infinity	5:50 PM	Next steps - AOB
4:50 PM	Saildrone		
5:00 PM	NOAA		
5:10 PM	MARUM		
5:20 PM	SEAPROVEN		
5:30 PM	Panel Discussion		
5:40 PM	Panel Discussion		
5:50 PM	Wrap up and closure		

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2:40 PM	GPASesbots	3:00 PM	NOAA
2:50 PM	ixblue	3:15 PM	LSTS FEUP
3:00 PM	UTEK	3:30 PM	Panel Discussion
3:10 PM	Seasets	3:40 PM	Panel Discussion
3:20 PM	Saildrone	3:50 PM	Wrap up and closure
3:30 PM	Panel Discussion	4:00 PM	Session 4 - Best Practices and ASV Network Roadmap Definition
Session 2 - ASV Applications / Operations		4:20 PM	EMODNet
4:00 PM	UEA	4:40 PM	ixblue
4:10 PM	GEOMAR	5:00 PM	NOAA
4:20 PM	XOCEAN Ltd.	5:20 PM	MARUM
4:30 PM	Tidewise	5:40 PM	Panel Discussion
4:40 PM	Ocean Infinity	5:50 PM	Next steps - AOB
4:50 PM	Saildrone		
5:00 PM	NOAA		
5:10 PM	MARUM		
5:20 PM	SEAPROVEN		
5:30 PM	Panel Discussion		
5:40 PM	Panel Discussion		
5:50 PM	Wrap up and closure		



ANTOINE THEBAUD está hablando...

 <p><b>CARLOS BARRERA</b></p>	 <p><b>JOÃO BORGES DE SOUSA</b></p>	 <p><b>CHRISTOPH WALDMANN</b></p>	 <p><b>RAFAEL COELHO</b></p>	 <p><b>RAMSAY LIND</b></p>
 <p><b>CHRISTIAN MEINIG</b></p>	 <p><b>SEBASTIAN MECKEL</b></p>	 <p><b>ANDY ZIEGWIED</b></p>	 <p><b>MICHAEL HUSKILSON</b></p>	 <p><b>SARAH HEASMAN</b></p>
 <p><b>ANDRES CIANCA</b></p>	 <p><b>DAVID MOTSON</b></p>	 <p><b>DECLAN KERWIN</b></p>	 <p><b>MICHAEL JONES</b></p>	 <p><b>PAU GUASCH</b></p>
 <p><b>PLOCAN</b></p>	 <p><b>INGA LIPS</b></p>	 <p><b>Aaron Chow</b></p>	 <p><b>ANDY CHIODI</b></p>	 <p><b>JEREMY JENKINS</b></p>
 <p><b>ESTELLE DUMONT</b></p>	 <p><b>DAVID PEDDIE</b></p>	 <p><b>BERNARDINO VALLE</b></p>	 <p><b>BJÖRN FIEDLER</b></p>	 <p><b>EUDELINE GUILLAUME</b></p>

# 1<sup>st</sup> USV WS - Main preliminary outcomes

- **Great level of interest, attendance and contribution** from current key USV-community members representing the “triple-helix” perspective (industry, academia/science and governance). Some other key members unable to attend but committed with future activities.
- The USV technology is already well developed and mature (**TRL 8-9**) in many cases.
- **Huge technological and operational capabilities** to cover in a synergistic way current ocean-observing gaps, being two of the main ones (1) to be able to monitor essential climate variables (ECV) and essential ocean variables (EOV) at the same time on an unprecedented space-time scale, and (2) act as gateway to link in real-time underwater observations with satellite platforms.
- Several helpful synergies already identified (and tested) with **other ocean-observing platforms** (fixed and mobile).
- **Wide range of applications/services for several Blue Growth sectors** on ocean-observing, survey, intervention, border security, etc. some of them already implemented in routine mode.
- Several technologies already as commercial product (important difference from other ocean-observing technologies).
- **Risk assessment and management system** is key.
- **Clear lack at network level** (main motivation to undertake this initiative under EuroSea project) from key aspects like technical -platforms and subsystems components-, coordinated operations/missions, data/metadata, legal framework (links with IMO/MASS strategy), best practices and standards, etc.



# OCEAN SCIENCES MEETING

FEBRUARY 27 - MARCH 4, 2022  
HONOLULU, HI, USA

COME TOGETHER *and* CONNECT


## OT05 - Uncrewed Surface Vehicles (USVs) Technology Trends and Improvements on Observing Applications for the Ocean Decade

March 2<sup>nd</sup> 2022 – 3:00-4:00 PM CET (Room 9) // 4:00-5:00 PM CET (Room 28)

<https://www.aslo.org/osm2022/scientific-sessions/#ot>

# EuroSea





## Integration and in-water testing of NOAA-PMEL's ASVCO2 (Autonomous Surface Vehicle Carbon Dioxide Sensor) into Wave Gliders and Sairdrones

**Christian Meinig, Noah Lawrence Slavas, Matt Casari, Adrienne Sutton, Stacy Maenner** (NOAA-Pacific Marine Environmental Laboratory)  
**Alex Turpin, Sophie Chu** (NOAA-PMEL & UW CICOES)  
**Kevin Rea** (Jupiter Research Foundation)  
**Richard Jenkins** (Sairdrone)


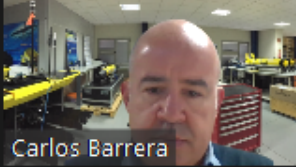
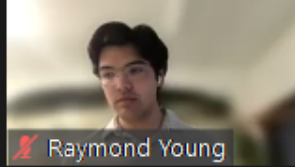



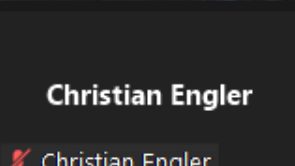
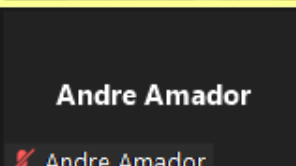
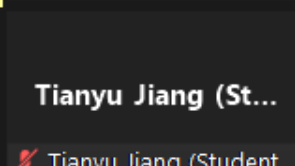
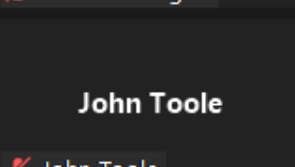
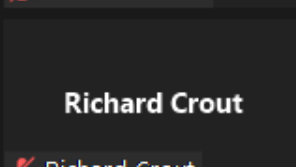
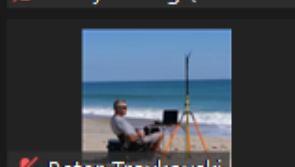
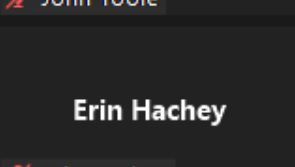
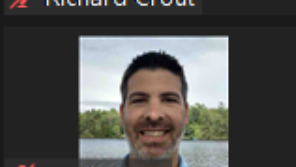
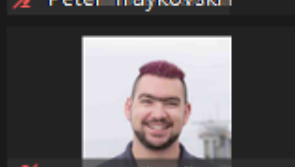
*Ocean Sciences  
March 2, 2022*

**Sponsors:**  
 NOAA-OA  
 NOAA-IOOS  
 NOAA-GOMO







 Andrew Chiodi	 Carlos Barrera	 Raymond Young
 Declan Kerwin	 Christian Meinig	 Christopher Waldmann
 Christian Engler	 Andre Amador	 Tianyu Jiang (Student...)
 John Toole	 Richard Crout	 Peter Traykovski
 Erin Hachey	 Mark Barry	 Raymond Leibensperger

# USV Developments

15th March 2022



Andrew Tyrer

Industrial Strategy  
Challenge Director  
- Robotics, UKRI



Carlos Barrera

Head of the  
Ocean Vehicles  
Unit - Oceanic  
Platform of the  
Canary Islands  
(PLOCAN)



Michael King

Senior Business  
Development  
Manager -  
Ocean Infinity



Stephane  
Vannuffelen

Marine  
Autonomy  
Technical  
Director - IxBlue



Stephen Thomson

Business  
Development  
Manager  
Renewables -  
Fugro

**O**i oceanology  
international  
2022

15-17 MARCH 2022  
LONDON, EXCEL

Sponsored by AUTONAUT



# Autonomous Surface Vehicles (ASV) Network

## 2<sup>nd</sup> Workshop

# EuroSea

April 13<sup>th</sup> and 14<sup>th</sup>, 2023  
 PLOCAN Headquarters  
 Gran Canaria, Spain

*In-person attendance event  
 (virtual access also available)*

*Travel grants available*

Contact:  
[andres.cianca@plocan.eu](mailto:andres.cianca@plocan.eu)

*DISCUSSION TOPICS*  
 Standard Operational Procedures  
 Data/Metadata Management  
 Legal Framework  
 Risk Assessment  
 Best Practices  
 Synergies and Services  
 ASV Network Roadmap - User Group  
 ...

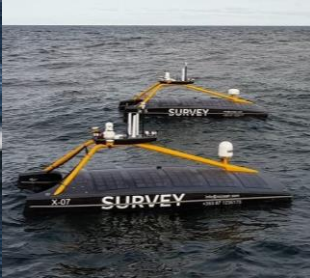
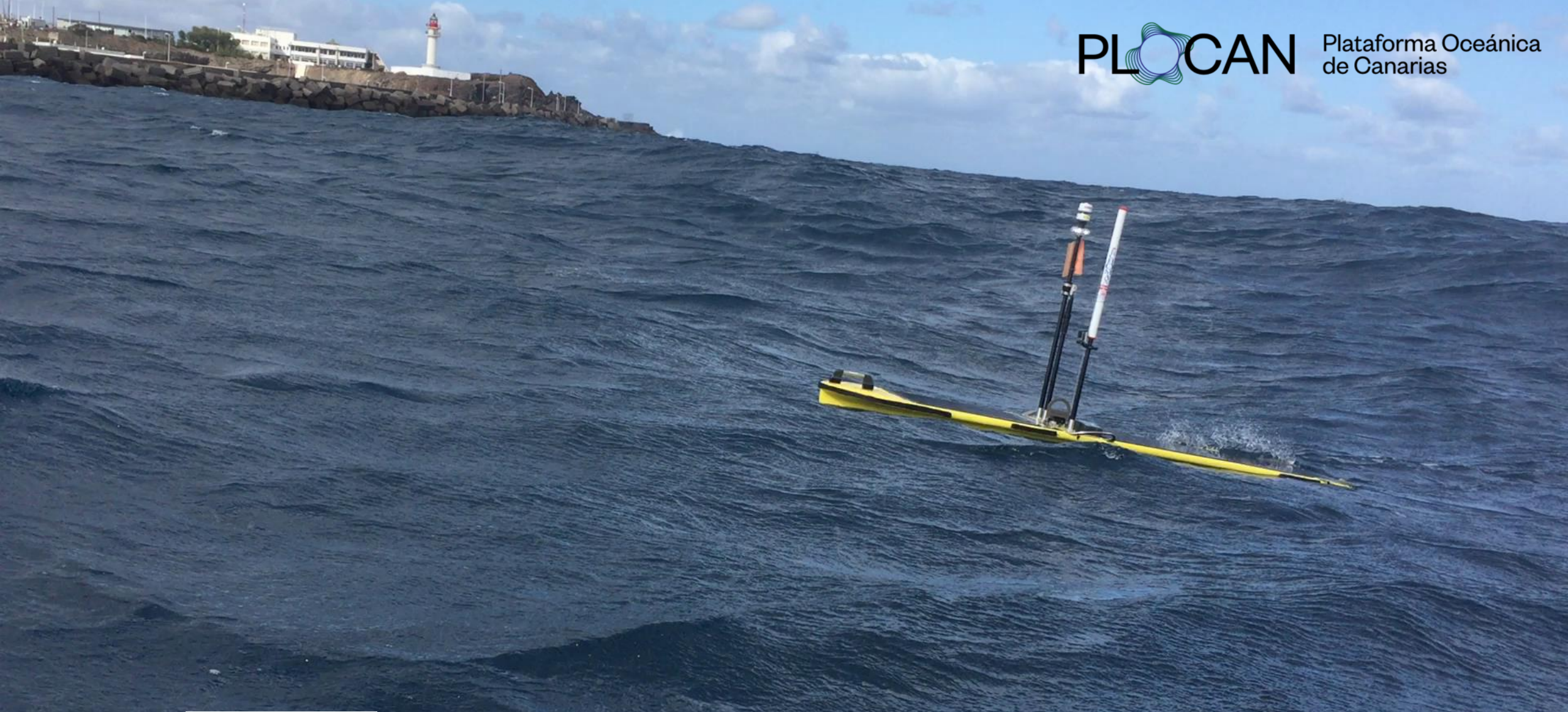


Organizers



Collaborators





Any  
questions?

Thank you

EuroSea

PLOCAN  
Plataforma Oceánica  
de Canarias



marum

U. PORTO  
FEUP FACULDADE DE ENGENHARIA  
UNIVERSIDADE DO PORTO

 National  
Oceanography Centre  
NATURAL ENVIRONMENT RESEARCH COUNCIL



 SCRIPPS INSTITUTION OF  
OCEANOGRAPHY  
UC San Diego

# MICEDD

## DEEPWATER DEVELOPMENT

28 - 30 March 2023 | Millennium Gloucester Hotel | London, UK

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